

### **Amendments to the Specification**

**Please amend the paragraph beginning on page 29, line 24 as follows:**

The third embodiment shown in Figs. 14 to 16 is substantially the same as the second embodiment shown in Figs. 10 to 13 in terms of the operations of the springs 33 and 34 in the manual operation mode but different from the second embodiment in that when the slide assembly 21 moves vertically in the motor-driven operation mode, the three members 41, 22 and 31a move vertically while being kept apparently unitary at all times; therefore, no compressive force is applied to the first-stage spring 33. In other words, the first-stage spring 33 has a constant length  $m$  throughout the movement of the slide assembly 21 between the initial position (Fig. 14) and the lower limit position (Fig. 16). Accordingly, the third embodiment has an advantage in that the driving torque of the motor 102 can be reduced, that is, the size of the motor 102 can be reduced correspondingly. Accordingly, it has ~~also~~ become possible in this case to use a pulse motor which can present relatively small driving torque.